Synchronization II

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Today’s Topics

- Spinlock is not enough
  - What if a lock is held by others?
  - What if a condition is not met inside the critical section?

- Higher-level synchronization mechanisms
  - Semaphores
  - Monitors
  - Condition variables and mutex
Higher-level Synchronization

**Motivation**

- Spinlocks and disabling interrupts are useful only for very short and simple critical sections.
  - Wasteful otherwise
  - These primitives are “primitive” – don’t do anything besides mutual exclusion.
- Need higher-level synchronization primitives that
  - Block waiters
  - Leave interrupts enabled within the critical section
- Two common high-level primitives:
  - Semaphores: binary (mutex) and counting
  - Monitors: mutexes and condition variables
- We’ll use our “atomic” locks as primitives to implement them.
Semaphores (1)

- Semaphores
  - A synchronization primitive higher level than locks.
  - Invented by Dijkstra in 1968, as part of the THE OS.
  - Does not require busy waiting.
  - Manipulated atomically through two operations:
    - Wait (S): decrement, block until semaphore is open
      = P(), after Dutch word for test, also called down()
    - Signal (S): increment, allow another to enter
      = V(), after Dutch word for increment, also called up()
Semaphores (2)

- **Blocking in semaphores**
  - Each semaphore has an associated queue of processes/threads.
  - When `wait()` is called by a thread,
    - If semaphore is “open”, thread continues.
    - If semaphore is “closed”, thread blocks, waits on queue.
  - `Signal()` opens the semaphore.
    - If thread(s) are waiting on a queue, one thread is unblocked.
    - If no threads are on the queue, the signal is remembered for next time a `wait()` is called.
  - In other words, semaphore has history.
    - The history is a counter.
    - If counter falls below 0, then the semaphore is closed.
    - `wait()` decreases the counter while `signal()` increases it.
Implementing Semaphores

typedef struct {
    int value;
    struct process *L;
} semaphore;

void wait (semaphore S) {
    S.value--;
    if (S.value < 0) {
        add this process to S.L;
        block ();
    }
}

void signal (semaphore S) {
    S.value++;
    if (S.value <= 0) {
        remove a process P from S.L;
        wakeup (P);
    }
}

wait() / signal() are critical sections! Hence, they must be executed atomically w.r.t. each other.

HOW??
Types of Semaphores

- **Binary semaphore (a.k.a mutex)**
  - Guarantees mutually exclusive access to resource.
  - Only one thread/process allowed entry at a time.
  - Counter is initialized to 1.

- **Counting semaphore**
  - Represents a resource with many units available.
  - Allows threads/processes to enter as long as more units are available.
  - Counter is initialized to \( N (= \text{units available}) \).
Bounded Buffer Problem (1)

- **Producer/consumer problem**
  - There is a set of resource buffers shared by producer and consumer.
  - Producer inserts resources into the buffer.
    - Output, disk blocks, memory pages, etc.
  - Consumer removes resources from the buffer.
    - Whatever is generated by the producer
  - Producer and consumer execute in different rates.
    - No serialization of one behind the other
    - Tasks are independent
    - The buffer allows each to run without explicit handoff.
Bounded Buffer Problem (2)

- No synchronization

```c
void produce(data) {
    while (count==N);
    buffer[in] = data;
    in = (in+1) % N;
    count++;
}

void consume(data) {
    while (counter==0);
    data = buffer[out];
    out = (out+1) % N;
    count--;
}
```
### Bounded Buffer Problem (3)

- **Implementation with semaphores**

```c
struct item buffer[N];
int in, out;

void produce(data)
{
    wait (empty);
    wait (mutex);
    buffer[in] = data;
    in = (in+1) % N;
    signal (mutex);
    signal (full);
}

void consume(data)
{
    wait (full);
    wait (mutex);
    data = buffer[out];
    out = (out+1) % N;
    signal (mutex);
    signal (empty);
}
```

- Semaphore
  - mutex = 1;
  - empty = N;
  - full = 0;
Readers-Writers Problem (1)

- Readers-Writers problem
  - An object is shared among several threads.
  - Some threads only read the object, others only write it.
  - We can allow multiple readers at a time.
  - We can only allow one writer at a time.

- Implementation with semaphores
  - readcount – # of threads reading object
  - mutex – control access to readcount
  - rw – exclusive writing or reading
Readers-Writers Problem (2)

```c
// number of readers
int readcount = 0;
// mutex for readcount
Semaphore mutex = 1;
// mutex for reading/writing
Semaphore rw = 1;

void Writer ()
{
    wait (rw);
    ...
    Write
    ...
    signal (rw);
}

void Reader ()
{
    wait (mutex);
    readcount++;
    if (readcount == 1)
        wait (rw);
    signal (mutex);
    ...
    Read
    ...
    wait (mutex);
    readcount--;
    if (readcount == 0)
        signal (rw);
    signal (mutex);
}
```
Readers-Writers Problem (3)

Note:

- If there is a writer
  - The first reader blocks on rw.
  - All other readers will then block on mutex.
- Once a writer exits, all readers can fall through.
  - Which reader gets to go first?
- The last reader to exit signals waiting writer.
  - Can new readers get in while writer is waiting?
- When writers exits, if there is both a reader and writer waiting, which one goes next is up to scheduler.
Dining Philosopher (1)

- Dining philospher problem
  - Life of a philosopher
    - Repeat forever:
      Thinking
      Getting hungry
      Getting two chopsticks
      Eating
Dining Philosopher (2)

- A simple solution

```c
Semaphore chopstick[N];  // initialized to 1
void philosopher (int i)
{
    while (1) {
        think ();
        wait (chopstick[i]);
        wait (chopstick[(i+1) % N];
        eat ();
        signal (chopstick[i]);
        signal (chopstick[(i+1) % N];
    }
}
```
### Dining Philosopher (3)

- **Deadlock-free version: starvation?**

```c
#define N 5
#define L(i) ((i+N-1)%N)
#define R(i) ((i+1)%N)

void philosopher (int i) {
    while (1) {
        think ();
        pickup (i);
        eat();
        putdown (i);
    }
}

void test (int i) {
    if (state[i]==HUNGRY &&
        state[L(i)]!=EATING &&
        state[R(i)]!=EATING) {
        state[i] = EATING;
        signal (s[i]);
    }
}

void pickup (int i) {
    wait (mutex);
    state[i] = HUNGRY;
    test (i);
    signal (mutex);
    wait (s[i]);
}

void putdown (int i) {
    wait (mutex);
    state[i] = THINKING;
    test (L(i));
    test (R(i));
    signal (mutex);
}
```

Semaphore mutex = 1;
Semaphore s[N];
int state[N];
Problems with Semaphores

- **Drawbacks**
  - They are essentially shared global variables.
    - Can be accessed from anywhere (bad software engineering)
  - There is no connection between the semaphore and the data being controlled by it.
  - Used for both critical sections (mutual exclusion) and for coordination (scheduling).
  - No control over their use, no guarantee of proper usage.

- **Thus, hard to use and prone to bugs**
  - Another approach: use programming language support
Monitors (1)

Monitor

- A programming language construct that supports controlled access to shared data.
  - Synchronization code added by compiler, enforced at runtime.
  - Allows the safe sharing of an abstract data type among concurrent processes.
- A monitor is a software module that encapsulates.
  - shared data structures
  - procedures that operate on the shared data.
  - synchronization between concurrent processes that invoke those procedures.
- Monitor protects the data from unstructured access.
  - guarantees only access data through procedures, hence in legitimate ways.
Monitors (2)

- **Mutual exclusion**
  - Only one process can be executing inside at any time.
    - Thus, synchronization implicitly associated with monitor
  - If a second process tries to enter a monitor procedure, it blocks until the first has left the monitor.
    - More restrictive than semaphores.
    - But easier to use most of the time.

- **Condition variables**
  - Once inside, a process may discover it can’t continue, and may wish to sleep, or allow some other waiting process to continue.
  - Condition variables are provided within monitor.
    - Processes can wait or signal others to continue.
    - Can only be accessed from inside monitor.
Monitors (3)

Queues associated with $x, y$ conditions

Shared data

Waiting queue of processes trying to enter the monitor

Operations

Initialization code

At most one process in monitor at a time
### Condition Variables

#### Purpose
- provides a mechanism to wait for events. (a “rendezvous point”)

#### Three operations:
- **wait (c)**
  - release monitor lock, so somebody else can get in.
  - wait for somebody else to signal condition.
  - thus, condition variables have wait queues.
- **signal (c)**
  - wake up at most one waiting process.
  - if no waiting processes, signal is lost.
  - this is different from semaphores: no history!
- **broadcast (c)**
  - wake up all waiting processes.
Monitor bounded_buffer {
    buffer resources[N];
    condition not_full, not_empty;

    procedure add_entry (resource x) {
        while (array “resources” is full)
            wait (not_full);
        add “x” to array “resources”;
        signal (not_empty);
    }

    procedure remove_entry (resource *x) {
        while (array “resources” is empty)
            wait (not_empty);
        *x = get resources from array “resources”
        signal (not_full);
    }
}
Monitors Semantics (1)

- **Hoare monitors:**
  - signal(c) immediately switches from the caller to a waiting thread, blocking the caller.
    - The condition that the waiter was anticipating is guaranteed to hold when waiter executes.
    - Signaler must restore monitor invariants before signaling.

- **Mesa monitors:**
  - signal(c) places a waiter on the ready queue, but signaler continues inside monitor.
    - Condition is not necessarily true when waiter runs again.
    - Being woken up is only a hint that something has changed.
    - Must recheck conditional case.
Monitors Semantics (2)

- **Comparison**
  - **Usage:**
    
    | Hoare monitors | Mesa monitors |
    |----------------|--------------|
    | if (notReady)  | while (notReady) |
    | wait (c);      | wait (c);      |

  - **Mesa monitors easier to use.**
    - more efficient
    - fewer switches
    - directly supports broadcast()

  - **Hoare monitors leave less to chance.**
    - when wake up, condition guaranteed to be what you expect.
Monitors using Semaphores

- Hoare monitors

Semaphore mutex = 1;
Semaphore next = 0;
int next_count = 0;
struct condition {
    Semaphore sem;
    int count;
} x = {0, 0};

procedure F () {
    wait (mutex);
    ...
    Body of F
    ...
    if (next_count)
        signal (next);
    else
        signal (mutex);
    wait (x.sem);
    x.count--;
}

procedure cond_wait (x) {
    x.count++;
    if (next_count)
        signal (next);
    else
        signal (mutex);
    wait (x.sem);
    x.count--;
}

procedure cond_signal (x) {
    if (x.count) {
        next_count++;
        signal (x.sem);
        wait (next);
        next_count--;
    }
}
Monitors and Semaphores

- **Comparison**
  - Condition variables do not have any history, but semaphores do.
    - On a condition variable `signal()`, if no one is waiting, the signal is a no-op.
      (If a thread then does a condition variable `wait()`, it waits.)
    - On a semaphore `signal()`, if no one is waiting, the value of the semaphore is increased.
      (If a thread then does a semaphore `wait()`, the value is decreased and the thread continues.)
Condition Variables and Mutex

- Yet another construct:
  - Condition variables can be also used without monitors in conjunction with mutexes.
  - Think of a monitor as a language feature
    - Under the covers, compiler knows about monitors.
    - Compiler inserts a mutex to control entry and exit of processes to the monitor’s procedures.
    - But can be done anywhere in procedure, at finer granularity.
  - With condition variables, the module methods may wait and signal on independent conditions.
Synchronization in Pthreads

```c
pthread_mutex_t mutex;
pthread_cond_t not_full, not_empty;
buffer resources[N];
void add_entry (resource x) {
    pthread_mutex_lock (&mutex);
    while (array "resources" is full)
        pthread_cond_wait (&not_full, &mutex);
    add "x" to array "resources";
    pthread_cond_signal (&not_empty);
    pthread_mutex_unlock (&mutex);
}
void remove_entry (resource *x) {
    pthread_mutex_lock (&mutex);
    while (array "resources" is empty)
        pthread_cond_wait (&not_empty, &mutex);
    *x = get resource from array "resources"
    pthread_cond_signal (&not_full);
    pthread_mutex_unlock (&mutex);
}
```
Synchronization Mechanisms

- Disabling interrupts
- Spinlocks
  - Busy waiting
- Semaphores
  - Binary semaphore = mutex (≪ lock)
  - Counting semaphore
- Monitors
  - Language construct with condition variables
- Mutex + Condition variables
  - Pthreads